



An Efficient OLSR Routing Protocol to Minimize Multipoint Relays in MANET

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Abstract: Reducing control packets, especially in proactive routing protocols, needed to establish routes can lower network overhead in Mobile Ad-hoc Networks (*MANETs*). In Optimized Link State Routing (*OLSR*) protocol, each Multipoint Relay (*MPR*) node propagates Topology Control (*TC*) messages to advertise neighbor information. However, *OLSR* controls the *TC* messages by reducing the number of *MPR* nodes. In this study, we propose an efficient *MPR* node selection mechanism to reduce the *TC* message volume leading to a minimized routing overhead. Each node selects the lowest cost node heuristically from its first hop neighbors as the *MPR* node for any destination. The same *MPR* node can be selected for multiple destinations if it costs the lowest for each destination node. The selection technique is realized by modifying only the default *OLSR TC* and *Hello* messages. The proof-of-concept implementation in the *NS3* simulator reveals that the proposed methodology reduces the routing overhead by selecting around 55%, 28% and 49% (on average) fewer *MPR* nodes compared to the traditional *OLSR*, *SSTB* and *M-OLSR* protocol respectively, without negotiating packet delivery ratio, throughput and delay.

Keywords: *MANET*, *OLSR*, *TC* Messages, Routing overhead, *MPR*.

1. Introduction

MANET [1] is a variant of ad-hoc networks where nodes are mobile and decentralized in type, and packet routing does not need any pre-established centralized infrastructure. *MANET* is autonomous, self-configurable, and highly adaptive, and the distinct features make it ideal for realization in scenarios where an infrastructure network is absent or failed, or establishment is challenging or impossible, for example, military applications [2], forest fire surveillance [3], search and rescue operations [4], disaster recovery and rescue operations [5], etc. The routing protocols [6] are responsible for delivering packets and maintaining the paths between communicating nodes in *MANET* [7-9].

Routing protocols in *MANET* can broadly be categorized into proactive, reactive, and hybrid routing protocols [10]. *OLSR* [11] is one of the most popular wireless routing protocols exhibiting comparatively better performance in *MANET*, and the

classical link state routing mechanism is optimized to develop *OLSR*. Being a proactive protocol, *OLSR* guarantees prior route availability every time. The prior route availability enables it to outperform its counterpart benchmarks in terms of packet delivery ratio (*PDR*), throughput, and end-to-end delay [12-15]. However, the table-driven characteristics cause *OLSR* to experience a higher routing overhead than those counterparts. Thus, the performance enhancement *OLSR* has become a highly debated research topic. This research chooses to address and improve the *OLSR* routing overhead issue without sacrificing other performance issues, for instance, *PDR*, throughput, and delay.

Nodes in *MANET* can establish and maintain required routes through a regular or periodic exchange of *Hello* and *TC* messages. However, the rise in *TC* messages, especially in dense networks, could lead to message collisions, traffic congestion, and increased energy use, which are potential reasons for performance degradation. *OLSR* controls or optimizes the *TC* message broadcasting by permitting only the selected *MPR* nodes to forward *TC* messages.

A single *TC* packet dispensed by an *MPR* node may encapsulate two or more *TC* messages, which aids in lowering the routing overhead and the likelihood of packet collision from different nodes. Thus, reducing the *MPR* set can reduce the number of *TC* messages.

The traditional *MPR* selection algorithm is unsuitable for keeping the *MPR* set small as it selects more *MPR* nodes needed to cover all possible 2-hop neighbors. A few heuristic solutions for selecting the best *MPR* are proposed in the literature; however, the schemes are sophisticated, challenging to use, and consume additional resources. Therefore, this work proposes an improved *MPR* selection technique covering only one-hop neighbors and effectively decreasing the number of control packets without sacrificing other performance metrics and is implemented by a network simulator named *NS3* (*NS-3.30*) [16]. The key contributions of this paper can be summarized as follows:

The size of *MPR* set is reduced since only the lowest cost node/s in the first-hop neighbor is considered as the *MPR* node/s.

The same *MPR* node can be used for multiple destinations if it is the lowest-cost node for each destination.

Only the default control messages are extended to realize the proposed strategy.

The proposed strategy is contrasted against the default *OLSR* and *M-OLSR* in terms of *PDR*, throughput, delay, and overhead, by varying the number of nodes and pause time.

The remaining part of this paper is organized as follows. Section 2 reviews the related literature of different optimizations in existing *OLSR*. The system model, assumptions, and problem formulation have been discussed in section 3. Section 4 presents the working methodology. Section 5 demonstrates the simulation results and finally, section 6 concludes the paper.

2. Related work

Several different sorts of research have been done in the last few decades to enhance the *OLSR* protocol's functionality on *MANET* networks. For enhancing the performance, researchers have focused more attentions in *MPR* selection strategy to reduce routing overhead in the network. Being a proactive protocol, *OLSR* maintains route quality and experience lower latency than their reactive counterparts, such as *DSR* and *AODV*, as routing information is available anytime. However, the proactive protocols show deteriorated performance regarding routing overhead [17]. This section

explores past efforts that made similar contributions to several *OLSR* routing schemes in ad-hoc networks.

The authors of this paper [18], introduce a new process of choosing *MPR* nodes, named *M-OLSR*, by giving higher priority to nodes that are more stable in terms of energy and mobility. The objective of this approach is to improve overall network performance by incorporating a mobility metric into the traditional *MPR* selection procedure. Based on the mobility degree captured or the node with the largest residual energy, this protocol gives priority to less mobile candidate *MPR* nodes. The drawback of this strategy is that, depending on the flow of motion around the node, the parameter λ (coefficient of flow) must be fixed between three values (0.25, 0.5, and 0.75). *M-OLSR* does not, however, adequately reduce the routing overhead (Fig. 12).

In [19], a new strategy called "Selector Set Tie Breaker" (*SSTB*) has been proposed for minimizing the global *MPR* set (the union of all the *MPR* sets). Prior to implementing the initial tie-break [20], an additional step is included that essentially favours the node with the greatest number of selectors among *MPRs* and the node that is already an *MPR* for another node. However, this mechanism reduces fewer number of *MPR* set compared to original *OLSR*, without considering other performance metrics and this *MPR* selection has been optimized in this study (Fig. 11) using heuristic concepts.

In this paper [21], the authors propose a quantum-genetic-based modified *OLSR* protocol to reduce the redundant information in *MANET*. According to an improved version of the quantum genetic algorithm, they introduced a new *MPR* selection scheme in which a newly designed Q-Learning technique has been adopted, and nodes are encoded by the quantum gene bit. A heuristic node fitness rule has been followed to select a small *MPR* set for each node. In this paper, network control overhead drastically increases with network size.

AOLSR, explained in [22], offers greater *MPR* selection criteria optimization. Less overhead is accomplished by placing the *MPR* node on either the left or right side of the sender node, depending on where the destination node is located. This protocol works well in terms of packet delivery ratio and throughput.

In [23], the authors propose a swarm-based hybrid *ACO PSO* meta-heuristic (*HAPM*) routing protocol to ensure routing in large and dynamic ad hoc network. To increase *QoS* restrictions and reduce *QoS* data dropping, this protocol combines *ACO*, *PSO*, and a dynamic queue mechanism. Although this protocol works well in large scale dynamic

environment, routing overhead has not been reduced up to the mark.

Additionally, the researchers have made several excellent attempts to select *MPRs* in order to improve the performance of the *OLSR* protocol while taking packet delivery ratio, routing overhead, throughput [24-26], energy efficiency [27], security issues [28] etc. into account.

The majority of previously referenced works for improving the earlier *MPR* selection strategy defined in standard *OLSR* protocol, which increases the number of chosen *MPR* nodes as well as introduce more complexities. So, we have applied heuristic concepts in *MPR* selection process which has been able to choose less number of *MPR* nodes as well as less *TC* message propagation compared to standard *OLSR* without degrading other performances.

3. System model, assumptions, and problem formulation

This section commences by briefly picturing the working procedure of the classical *OLSR* algorithm.

3.1 Network topology

OLSR enables proactive routing to determine the best path by spreading various types of control messages such as Hello, TC, MID, and HNA. The MANET nodes exchange neighbor and routing information through the control messages. The nodes utilize the control packets to build and keep the topology information in their routing tables. The network topology in Fig. 1 illustrates the proposed *MPR* selection technique where data from a sender finds the best paths to the given destinations.

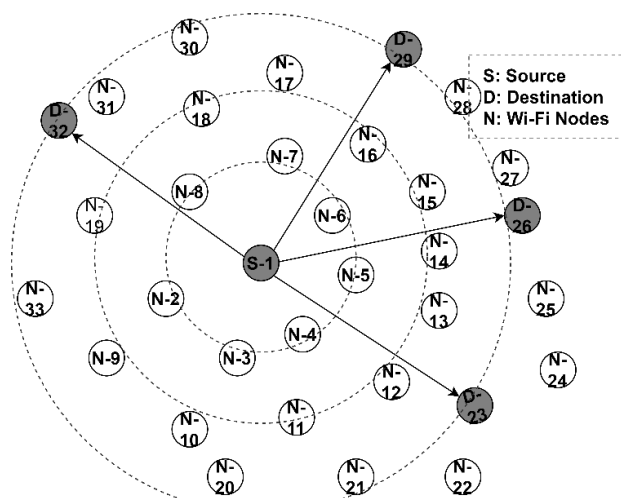


Figure. 1 Network topology

3.2 Existing *MPR* selection strategy used by *OLSR*

(*MPRs*) nodes are vital to reduce the dissemination of control *TC* messages. The classical *MPR* selection algorithm is heuristic in manner [11] where a node (*u*) needs to maintain its one-hop and two-hop neighbor sets, denoted as $N(u)$ and $N2(u)$, respectively. $N2(u)$ includes nodes reachable by the members of one-hop neighbors $N(u)$, and whose willingness is not *WILLNEVER*. Each node maintains the "willingness" parameter, an integer value that ranges from 0 to 7, indicating its eagerness to forward traffic on behalf of other nodes. Any node not interested in forwarding traffic for other nodes, such as because of resource limitations, is indicated by *WILLNEVER*(0). *WILLALWAYS*(7) denotes that a node is always ready to carry traffic on behalf of other nodes. By default, every node has the willingness set to *WILLDEFAULT*(3). When any node *y* is a member of $N(u)$, its degree is denoted as $D(y)$. $D(y)$ defines the number of symmetric neighbors of node *y*, omitting any other nodes that are also members of $N(u)$, and the node *u* doing the computation. The detailed classical *MPR* selection algorithm has been given in Algorithm 1.

Algorithm 1: Classical *MPR* selection strategy defined in *RFC 3626* [11]

```

1: Start with  $MPR(u) \leftarrow N(u)$  where willingness
   of  $y \in N(u)$  is WILLALWAYS
2: Compute  $D(y)$  for all  $y \in N(u)$ 
3: for Each  $y \in N(u)$  do
4:   if y is the only node to reach some  $w \in$ 
      $N2(u)$  then
5:     Add y to  $MPR(u)$  and Remove w from
      $N2(u)$ 
6:   end if
7: end for
8: while  $N2(u)$  remains not empty do
9:   if Only  $y \in N(u)$  has highest reachability
     and willingness for some  $w \in N2(u)$  then
10:    Add y to  $MPR(u)$  and Remove w from
      $N2(u)$ 
11:    if More  $y \in N(u)$  with same reachability
     and willingness then
12:      Find  $y \in N(u)$  where  $D(y)$  is
     maximum
13:      Add y to  $MPR(u)$  and Remove w from
      $N2(u)$ 
14:    end if
15:  end if
16: end while
17: Integrate  $MPR(u)$  for all interfaces of u

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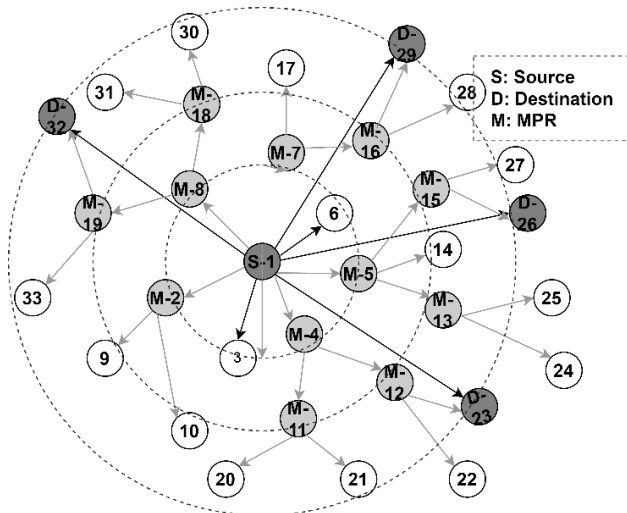


Figure. 2 Existing OLSR

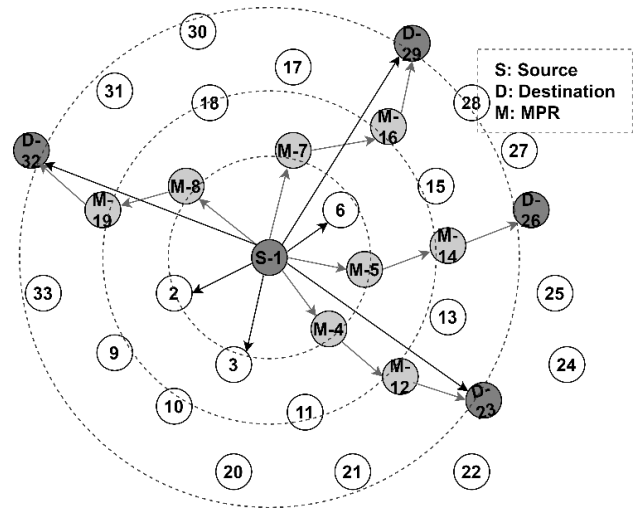


Figure. 3 Proposed OLSR

3.3 Problem definition

The classical *MPR* selection algorithm explained in section 3.2. results in many *MPR* nodes being selected for *TC* dissemination. Here, all the two-hop neighbors need to be covered by *MPR* nodes. However, the proposed methodology selects only those nodes as *MPR* needed to obtain optimal paths toward the destinations. The *MPR* and route selection scenarios of the classical and proposed algorithms are pictorially presented in Figs. 2 and 3 respectively. A node y in the proposed technique uses a heuristic function to select *MPR* nodes from its one-hop neighbor set, $N(u)$, explained in 4. Each node selects the lowest cost node from its $N(u)$ neighbor set as the *MPR* node for a particular destination node. The same *MPR* node can be selected for multiple destinations if it costs the lowest for each destination node. Only nodes that reside along the optimal path are selected as *MPR* nodes in this process. Therefore, the number of *MPR* nodes can be drastically reduced by pruning unnecessary or sub-optimal paths toward the destinations. If n and $|MPR(y)|$ represent the number of sinks and *MPR* nodes of y , respectively, then $|MPR(y)| \leq n$ for each node, y . In contrast, in classical OLSR, $|MPR(y)| \propto N^2(u)$. Thus, the number of *MPR* nodes selected in the proposed strategy is not dependent on the $N^2(u)$ set, rather it leans on the number of sinks resulting in a smaller-sized *MPR* set.

4. Proposed method

This section introduces the needed modifications of *Hello* and *TC* messages to execute the proposed technique. The modifications and the *MPR* selection strategy collectively aid in lowering the number of *MPR* nodes to diffuse fewer *TC* messages.

4.1 Extended Hello message format

As nodes' locations are at the heart of the proposed *MPR* selection process, every node must know its neighbors' and destination nodes' locations. In this study, each node is assumed to be equipped with a *GPS* receiver to obtain its location information; longitude and latitude positions. A node maintains and shares its neighbors' and destination locations by broadcasting periodic *Hello* messages. A new table, named *Dest_Table* (Fig. 6), is introduced to maintain the destinations' location information. In addition, the default neighbor table (Fig. 4) is extended by adding two fields to store neighbors' location and node costs. Fig. 5 exhibits the proposed *Hello* message to accommodate the location information.

$Location(X)$ and $Location(Y)$ represent the $longitude(X)$ and $latitude(Y)$ co-ordinates, respectively of the sender node. A node retrieves its neighbors' location information once a *Hello* is received. The *NodeCost* field is used to share the link cost established for each neighbor node. *Node Cost* is calculated using Eq. (3) as explained in section 4.3.3. *IsDest* represents a boolean value that determines whether the *Hello* message's sender is a destination. *DestMsgSize* contains the size of *Dest_Table* of the sender node. This field helps a receiver node to store sender's *Dest_Table* related information. The information of each tuple in *Dest_Table* is shared through $DestinationLocation(X)$, $DestinationLocation(Y)$, and $DestinationInterfaceAddress$ fields, respectively. The rest of the fields are similar to the original *Hello* message format.

Neighbor Main Address (32 bit)	Status (2 bit)	Willingness (8 bit)	Node Cost (16 bit)	Neighbor Location (32 bit)
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Figure. 4 Extended *Neighbor_Table* format

0										1										2										3									
Reserved										Htime										Willingness																			
Location(X)										Location(Y)																													
Node Cost										Is Dest										Dest Msg Size																			
Destination Location(X)										Destination Location(Y)																													
Destination Interface Address																																							
...																																							
Destination Location(X)										Destination Location(Y)																													
Destination Interface Address																																							
...																																							
Link Code					Reserved					Link Message Size																													
Neighbor Interface Address																																							
Neighbor Interface Address																																							
...																																							
Link Code					Reserved					Link Message Size																													
Neighbor Interface Address																																							
Neighbor Interface Address																																							
...																																							
etc.																																							

Figure. 5 Extended *Hello* message format

4.2 Proposed table formats

The *MPR* selection technique is realized by each node maintaining three new tables named *Dest_Table*, *MPR_Table*, and *Cost_Table*. The tables' purposes are described in the following sections.

4.2.1 Proposed table formats

Dest_Table stores information related to the specified destinations, as represented in Fig. 6. A *Hello* message uses the table's information to broadcast destination-related information. Also, the table is used for *MPR* calculation. *IPv4* address and location collected via the exchanges of *Hello* messages. When a node receives a *Hello* message, it first determines whether the sender is a destination node by inspecting the *IsDest* field of the *Hello* message. If the sender is the destination node, it updates its *Dest_Table* with the destination address and location. The node later shares the destination information by broadcasting *Hello* messages to its neighbors. The process continues, and each node is informed about the destinations once the network converges.

Destination Node Address (32 bit)	Destination Node Location (32 bit)
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Figure. 6 *Dest_Table* format

MPR Selector Address (32 bit)	Destination Address (32 bit)	Cost (8 bit)	Node Cost (From Source) (8 bit)	Destination Location (32 bit)
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Figure. 7 *MPR_Table* format

4.2.2 *MPR_Table* format

This table consists of five fields as represented in Fig. 7. A node's *MPRSelectorAddress* field stores the *IPv4* address of the node that has selected it as the *MPR.DestinationAddress* and *DestinationLocation* fields refer to the information of a destination node for which this node has been selected as *MPR*. *Cost* and *NodeCost* fields store the total cost (Eq. (1)) and link cost (Eq. (3)) between the selector node and the node itself. The cost calculation process is given in section 4.3.3. A node may update its *MPR_Table* once it receives a *TC* message from its neighbors. Since the source node cannot be selected as *MPR* node, its *MPRSelectorAddress* field always contains *NULL* value, or equivalently "0.0.0.0". Initially, the source nodes create a separate tuple in their *MPR* table with *MPRSelectorAddress* = "0.0.0.0". *MPR_Table* enables a node to know if it is a *MPR* node or not. This table, also, decides *TC* generation. A node runs Algorithm 4 in association with Eq. (1) to select the next *MPR* node using the table entries.

4.2.3 *Cost_Table* format

This table (Fig. 8) stores the next selected *MPR* information. For example, if a node *b* is selected as an *MPR* by node *a* for a particular destination node *c*, then *DestNodeAddress* and *NextNodeAddress* fields are populated by *c* and *b*, respectively. *Cost* field stores the cost-related information (Eq. (1)) for selecting the next *MPR* node. A node updates its *Cost_Table* utilizing the information stored in *Neighbor_Table* and *MPR_Table* using Algorithm 4.

4.3 Extended *TC* message format

This section introduces the modified *TC* message as given in Fig. 9. Only the *MPR* nodes generate *TC* messages containing the information stored in *Cost_Table*, *MPR_Table* and *Neighbor_Table*. A node shares its selected *MPR* set with its neighbor nodes through *TC*. A neighbor node receiving the *TC* message updates its *MPR_Table* if its *IPv4* address is piggybacked in this message. *TC* modification or extension increases its size; however, the demerit is counteracted by reducing the number of *MPR* nodes (and hence *TC* messages). The sender node shares its own *IPv4* address, and the *MPR* set through *MPRSelectorNodeAddress* and *MPRNodeAddress* fields, respectively. *DestinationNodeAddress* contains the address of the destination node for which *MPR* has been selected. *NodeCost* field contains the cost between the sender node and the selected *MPR* node, and *Cost* field contains the total cost to select an *MPR*.

Destination Node Address (32 bit)	Next Node Address (32 bit)	Cost (8 bit)
--------------------------------------	-------------------------------	-----------------

Figure. 8 *Cost_Table* format

0	1	2	3
0 1 2 3 4 5 6 7 8 9	0 1 2 3 4 5 6 7 8 9	0 1 2 3 4 5 6 7 8 9	0 1
ANSN		Reserved	
Advertised Neighbor Main Address			
Advertised Neighbor Main Address			
...			
MPR Node Address			
MPR Selector Node Address			
Destination Node Address			
Node Cost		Cost	

Figure. 9 Extended *TC* message format

4.3.1 Extended *TC* message format

TC message can only be generated and circulated by the selected *MPR* nodes and the source node. This can be implemented by checking the size of *MPR_Table* i.e. $|MPR_Table|$ for each node. If $|MPR_Table| \neq \emptyset$, only then it can send *TC* messages to its neighbors. A node can be identified as an *MPR* only if $|MPR_Table| \neq \emptyset$ and *MPRSelectorAddress* $\neq "0.0.0.0"$. *TC* messages are generated on basis of the information stored in *Neighbor_Table*, *MPR_Table*, and *Cost_Table*. The detailed *TC* message generation technique has been explained in Algorithm 2. This approach states that a node *y* checks its $|MPR_Table| \neq \emptyset$ to generate the *TC* messages. For each tuple *i* of node *y*'s *Cost_Table*, the values of *NextNodeAddress*, *DestinationNodeAddress* and *Cost* fields are shared, respectively, through the *MPRNodeAddress*, *DestinationNodeAddress* and *Cost* fields of the generated *TC*. *MPRSelectorNodeAddress* field of *TC* contains the main address of node *y* and *NodeCost* represents the link cost. The remaining fields contain information following *RFC 3626* [11].

4.3.2 *TC* processing technique

Upon receipt of a *TC* message, a node *y* processes it only if its *IPv4* address is listed in the *MPRNodeAddress* field of the message. If the receiver node finds itself as listed, then it confirms itself to be an *MPR* node selected by the *TC* sending node and starts to process *TC* and updates its *MPR_Table*. Algorithm 3 shows the processing technique of the received *TC* message to update *MPR_Table*. For each row *i* of the received *TC*, a new tuple *j* is inserted into the node *y*'s *MPR_Table*. *MPRSelectorAddress*, *DestinationAddress*, *Cost*, *NodeCost* fields of each tuple *j* in *MPR_Table* of *y*

stores the received information carried by *MPRSelectorNodeAddress*, *DestinationNodeAddress*, *Cost*, *NodeCost* fields, respectively, of each *i* of the received *TC*. *DestinationLocation* field of tuple *j* updates from node *y*'s *Dest_Table*. The remaining information is processed according to the basic *TC* message processing technique stated in [11].

4.3.3 Proposed cost function

The proposed *MPR* selection technique, illustrated in Algorithm 4, is based on the heuristic cost function presented in Eq. (1). For example, if *j* is selected as the next *MPR* of *i* for a particular destination *k*, then the cost for selecting *j* is the sum of the residual cost between *j* and *k* and node cost between *i* and *j*. It is assumed that the cost is directly proportional to Euclidean distance; the cost increases as the distance between two nodes increases. Euclidean distance between any two nodes is calculated as:

$$Cost^j = NodeCost^{i,j} + ResidualCost^{j,k} \quad (1)$$

$$D(p, q) = \sqrt{(q_x - p_x)^2 + (q_y - p_y)^2} \quad (2)$$

$$NodeCost^{i,j} = \frac{D(i,j)}{\alpha^j} \quad (3)$$

$$\alpha^j = 2 \times w^j + 1, w^j = willingness^j \quad (4)$$

$$ResidualCost^{j,k} = \frac{D(j,k)}{\beta} \quad (5)$$

$$Cost_{NextMPR^i} = \min_{\forall j \in N(i)} Cost^j \quad (6)$$

In Eq. (3), node cost represents the cost between any two 1-hop neighbor nodes. Node cost is directly proportional to the distance between these two nodes and inversely proportional to the willingness factor, α , of the reaching node. α is a function of willingness (Eq. (4)) of the neighbor node to forward a *TC* message. According to Eq. (3), if the willingness of neighbor node increases, node cost decreases, i.e., the possibility of being selected as *MPR* increases. On the other hand, node cost is high for a higher distance leading to a lesser possibility in *MPR* selection.

Residual cost (Eq. (5)) between the 1-hop neighbor *node(j)* and the destination *node(k)* is directly proportional to the Euclidean distance and inversely proportional to a normalization factor, β . If $D(j, k)$ increases, it means that, node *j* is far away from destination *k*. This results in a lesser possibility

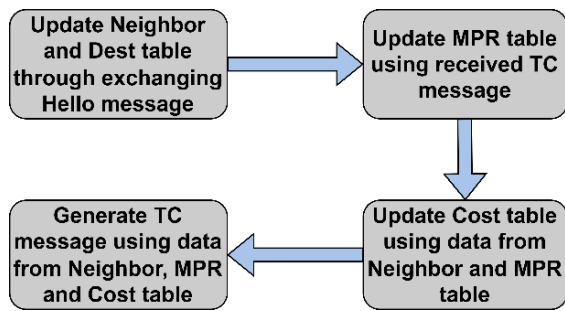


Figure. 10 The basic working process for calculating MPR

to select j as an MPR node for i . The normalization factor β depends on the nodes' transmission power and network area. In this study, β is determined heuristically.

Finally, the cost of the selected next MPR node of i is calculated using Eq. (6). Here, $N(i)$ represents all 1-hop neighbors of node i . From all the symmetric 1-hop neighbors of i , the selected next MPR is j , if the cost to reach j is lowest.

4.3.4 MPR calculation technique

A node calculates MPR periodically after each $TC_Interval$ stated in the classical OLSR. Initially, the MPR is calculated according to the heuristic Algorithm 4, a node finds its next MPR set and updates $Cost_Table$ to store MPR information as follows. A node finds its next MPR node based on a heuristic function stated in Eq. (1). The cost calculation process for selecting next MPR node follows Eq. (6).

If i and j represents each tuple of node y 's MPR_Table and $Neighbor_Table$ respectively, then it needs to find the lowest cost node j for each tuple i . Node y finds total cost for reaching each destination, stored in its MPR_Table , through each 1-hop neighbor j and finds the lowest cost neighbor j for each destination using Eq. (6). If y finds the lowest cost node p , from its all the 1-hop neighbors j , for a destination node q , then it considers node p as next MPR node for q . node y updates its $Cost_Table$'s $NextNodeAddress$ and $DestinationNodeAddress$ fields with p and q respectively. $Cost$ field contains the lowest cost for selecting p as next MPR node.

The basic working procedure is represented in Fig. 10. The neighbor table gets updated via continuous exchange of *Hello* messages. Each node can store neighbor information, including neighbor location and destination information, through exchanging *Hello* messages. Each node gets the information of the available destinations in the network as explained in section 4.2.1.

MPR_Table of a node is updated using the information piggybacked in the *TC* message. A node runs Algorithm 4 to find out the next MPR nodes based on the $Neighbor_Table$ and MPR_Table tables. Each node with $|MPR_Table| \neq \emptyset$ sends this MPR-related information to its neighbors using *TC* message. After receiving a *TC* message, a node can update its MPR_Table only if it is listed in this message.

Algorithm 2: TC message (TC Msg) generation

```

1: if  $|MPR\_Table| \neq \emptyset$  then
2:   for  $i = 1, 2, \dots$  do
3:     #i represents each tuple in  $Cost\_Table$ .
4:      $MPRNodeAddress (TC\ Msg) \leftarrow$ 
        $NextNodeAddress^i (Cost\_Table)$ 
5:      $MPRSelectorNodeAddress (TC\ Msg) \leftarrow$ 
        $SenderNodeAddress$ 
6:      $DestinationNodeAddress (TC\ Msg) \leftarrow$ 
        $DestinationNodeAddress^i (Cost\_Table)$ 
7:      $Cost (TC\ Msg) \leftarrow Cost^i (Cost\_Table)$ 
8:     for  $j = 1, 2, \dots$  do
9:       #j represents each tuple in  $MPR\_Table$ .
10:      if  $DestinationNodeAddress^i (Cost\_Table) =$ 
          $DestinationNodeAddress^j (MPR\_Table)$  then
11:        for  $k = 1, 2, \dots$  do
12:          #k represents each tuple in
            $Neighbor\_Table$ .
13:          if  $NextNodeAddress^i (Cost\_Table) =$ 
              $NeighborMainAddress^k (Neighbor\_Table)$  then
14:             $NodeCost (TC\ Msg) \leftarrow NodeCost^i$ 
               $(MPR\_Table) + NodeCost^k (Neighbor\_Table)$ 
15:            break
16:          end if
17:        end for
18:      break
19:    end if
20:  end for
21: end for
22: end if
  
```

Algorithm 3: TC message (TC Msg) processing

```

1: for  $i = 1, 2, \dots$  do
2:   #i represents each tuple in TC message.
3:   if  $ReceiverNodeAddress =$ 
      $MPRNodeAddress^i (TC\ Msg)$  then
4:      $MPRSelectorAddress (MPR\_Table) \leftarrow$ 
        $SenderNodeAddress$ 
5:      $DestinationAddress (MPR\_Table) \leftarrow$ 
        $DestinationNodeAddress^i (TC\ Msg)$ 
6:      $Cost (MPR\_Table) \leftarrow Cost^i (TC\ Msg)$ 
7:      $NodeCost (MPR\_Table) \leftarrow NodeCost^i (TC$ 
        $Msg)$ 
  
```

```

8:   for j = 1, 2, ..., do
9:     #j represents each tuple in Dest_Table.
10:    if DestinationNodeAddressi (TC Msg) =
DestinationNodeAddressi (Dest_Table) then
11:      DestinationLocation (MPR_Table) ←
DestinationNodeLocationj (Dest_Table)
12:      break
13:    end if
14:  end for
15:  break
16: end if
17: end for
    
```

Algorithm 4: Next MPR node Calculation

```

1: for i = 1, 2, ..., do
2:   #i represents each tuple in MPR_Table.
3:   for j = 1, 2, ..., do
4:     #j represents each tuple in
Neighbor_Table.
5:     Calculate the Cost of each j node
according to Eq.(1) and find out the minimum
cost node k using Eq.(6)
6:   end for
7:   Insert the tuple of Cost_Table as below: Step
8-10
8:   DestinationNodeAddress (Cost_Table) =
DestinationAddressi (MPR_Table)
9:   NextNodeAddress (Cost_Table) =
NeighborMainAddressi (Neighbor_Table) which
has been
selected as k
10:  Cost (Cost_Table) =The Calculated Cost for
reaching this node k
11: end for
    
```

Table 1. Simulation parameters

Platform used	Ubuntu-18.04
Type of network	MANET
Simulator used	NS-3.30
Simulation time	120 s
Total area	500*500 sq. m.
Number of nodes	50, 60, 70, 80, 90, 100
Transmit power	7.5 dBm
Mobility model	Random waypoint
Type of MAC	IEEE 802.11b
Transport layer	UDP
Total packet size	64 bytes
Pause Time	1, 5, 10 s
Stream index	0-9
Speed	4 m/s
Data rate	2048 bps
β	5

5. Simulation and results

5.1 Simulation parameters

Simulation experiments have been conducted using NS3 (version 3.30) network simulator to validate our proposed MPR selection technique. Then, we compared the obtained results with standard OLSR. All simulation parameters have been summarized in Table 1.

5.2 Simulation results

Experiment results presented in this paper are taken as the average values after running the simulator 10 times for each scenario.

Fig. 11 demonstrates the comparison of the total number of selected MPR nodes between classical OLSR and proposed efficient OLSR. Experiment results show that, the selection of MPR nodes increases with increasing number of nodes, as, more nodes are needed to establish routes towards destinations. However, among all available nodes in the network, only a few nodes are selected as MPRs using our methodology. As, our proposed approach selects MPR from neighbor nodes using a heuristic cost function, only the nodes having less cost can be elected as MPRs for the particular destination nodes. Thus, all the optimal paths, established using the cost function stated in Eq. (1), towards each destination node, are composed of these selected MPR nodes. Consequently, all the necessary routes, needed for data forwarding, are being established with less number of selected MPR nodes. This scenario validates the thought that our proposed MPR selection technique outperforms the classical OLSR, SSTB and M-OLSR protocol in terms of 55% (on average), 28% (on average) and 49% (on average) less MPR selection respectively which causes less overhead or less propagation of TC messages.

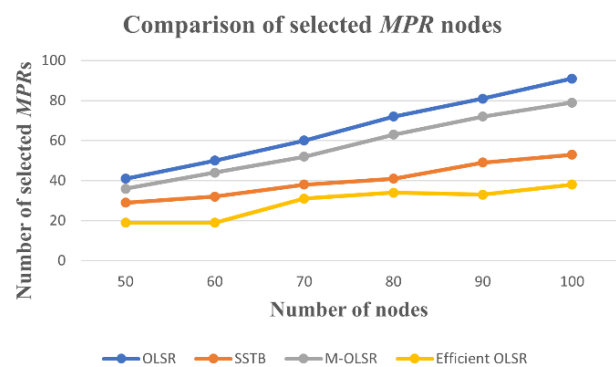


Figure. 11 Total selected MPR nodes

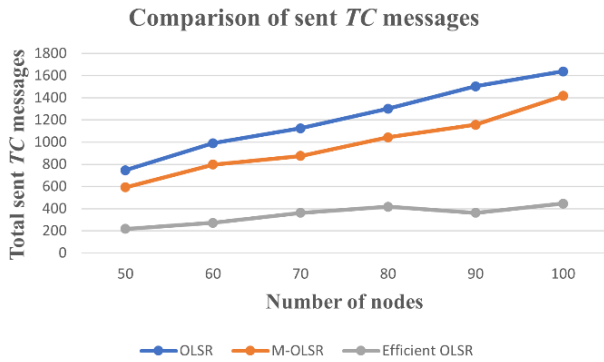


Figure. 12 Total sent TC messages

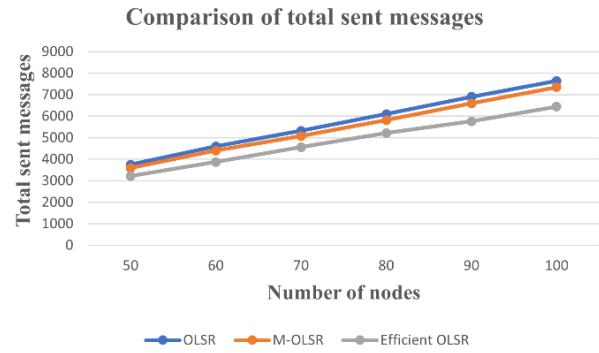


Figure. 14 Total sent messages

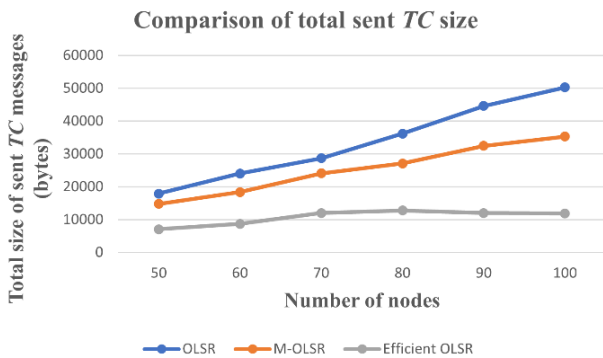


Figure. 13 Total size of sent TC messages

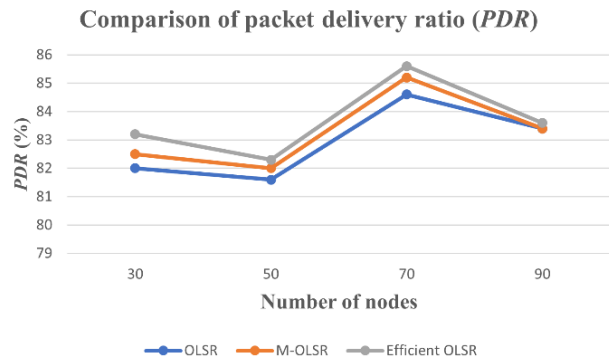


Figure. 15 Packet delivery ratio as a function of node number

Fig. 12 illustrates the total number of TC messages sent according to a different number of nodes both for standard OLSR and the proposed efficient OLSR. This result shows that TC dissemination increases according to the increasing node number for both protocols. Because, if number of node increases, it causes a rise in MPR selection. So, more TC messages are required to share network topology information. Moreover, the proposed method reduces the total TC dissemination for all cases. This is because, our proposed OLSR protocol selects less number of MPR nodes which absorb unnecessary TC flooding in the network. Consequently, our proposed protocol achieves up to 75% and 68% less TC propagation compared to the standard OLSR and M-OLSR protocol respectively.

Fewer TC dissemination also causes a reduction in the total size of the sent TC messages. This reduction in TC size is illustrated by Fig. 13. As the number of MPR nodes are reduced using the proposed protocol, it causes a reduction in the total number of flooded TC messages as well as TC size resulting less routing overhead.

Fig. 14 shows the comparison of total sent messages (Hello and TC) in the network. As, network density increases with higher number of nodes, number of sending messages also increases for

establishing necessary routes. However, the experiment results show that our methodology produces up to 16% and 11% fewer messages than standard OLSR and M-OLSR respectively. Only Hello and TC messages are taken under consideration in calculating total messages for their significant impacts on routing overhead. This reduction in the total number of message dissemination causes less processing time as well as lower overhead.

On the other hand, packet delivery ratio increases with increasing pause time (Fig. 16). Because, if pause time increases, the possibility of link breaking

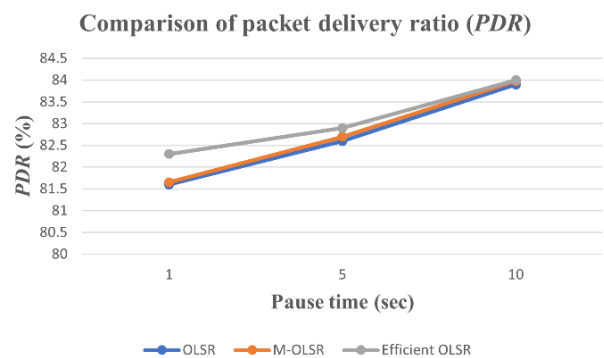


Figure. 16 Packet delivery ratio as a function of pause time

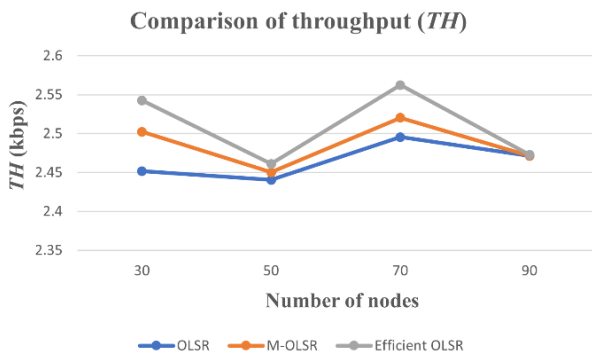


Figure. 17 Throughput as a function of node number

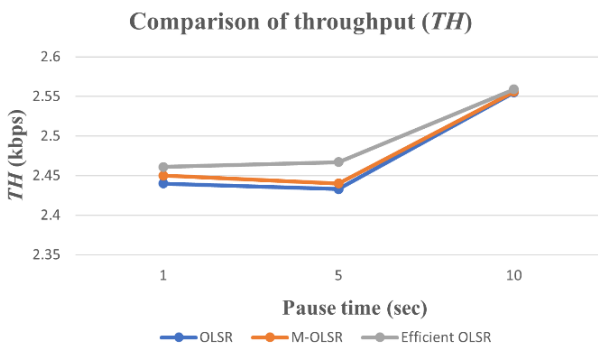


Figure. 18 Throughput as a function of pause time

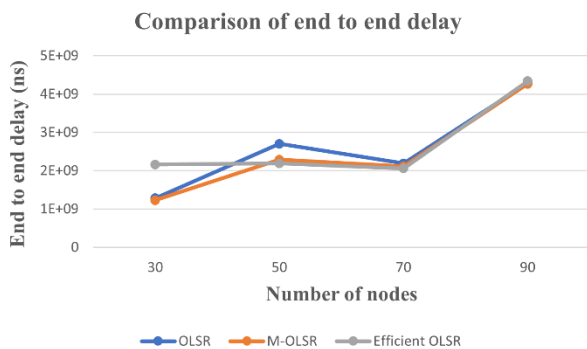


Figure. 19 Delay as function of node number

reduces, that, supports establishing optimal paths and increases packet delivery ratio.

Fig. 17 and Fig. 18 demonstrate the performance of the proposed *OLSR*, classical *OLSR* and *M-OLSR* in terms of throughput. These results depict that, throughput is being increased slightly in terms of both node number and pause time. From Fig. 18, it shows that, pause time creates more impacts on increasing throughput. Because, more stable links are established when pause time increases.

End-to-end delay is also compared in terms of node number in Fig. 19. Delay increases with increasing node number, as, the possibility of false *MPR* selection also increases. This causes

establishing non-optimal routes which increases end-to-end delay for data transmission.

6. Conclusion

This paper proposes an improved *MPR* selection strategy for *OLSR* protocol to enhance its performance in terms of network overhead in *MANET*. The major contribution is to reduce the number of selected *MPR* nodes, which disseminates fewer *TC* messages without affecting the other performance matrices. The proposed *MPR* selection strategy requires additional repositories and header extensions of *Hello* and *TC* messages. The technique works according to a Euclidean distance-based heuristic function.

The experiment results show that routing overhead is reduced by 75% and 68% (as maximum) compared to the classical *OLSR* and *M-OLSR* protocols respectively. Our proposed *MPR* selection strategy also shows good performance compared to the standard *OLSR* and *M-OLSR* protocols in terms of packet delivery ratio, throughput and delay.

As the cost function is vital to the proposed *MPR* selection technique, in the future, the normalization and willingness factors and hence the cost function will be determined considering network area, node speed, and transmission power.

Conflicts of Interest

The authors declare no conflict of interest.

Author Contributions

Conceptualization, Md. Zahid Hassan, Shahid Md. Asif Iqbal and Asaduzzaman; methodology, Md. Zahid Hassan; software, Md. Zahid Hassan and Shahid Md. Asif Iqbal; validation, Md. Zahid Hassan, Shahid Md. Asif Iqbal, and Asaduzzaman; formal analysis, Md. Zahid Hassan and Asaduzzaman; investigation, Md. Zahid Hassan and Asaduzzaman; resources, Md. Zahid Hassan; data curation, Md. Zahid Hassan; writing—original draft preparation, Md. Zahid Hassan; writing—review and editing, Md. Zahid Hassan, Shahid Md. Asif Iqbal and Asaduzzaman; visualization, Md. Zahid Hassan and Asaduzzaman; supervision, Shahid Md. Asif Iqbal and Asaduzzaman; project administration, Md. Zahid Hassan, Shahid Md. Asif Iqbal and Asaduzzaman.

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